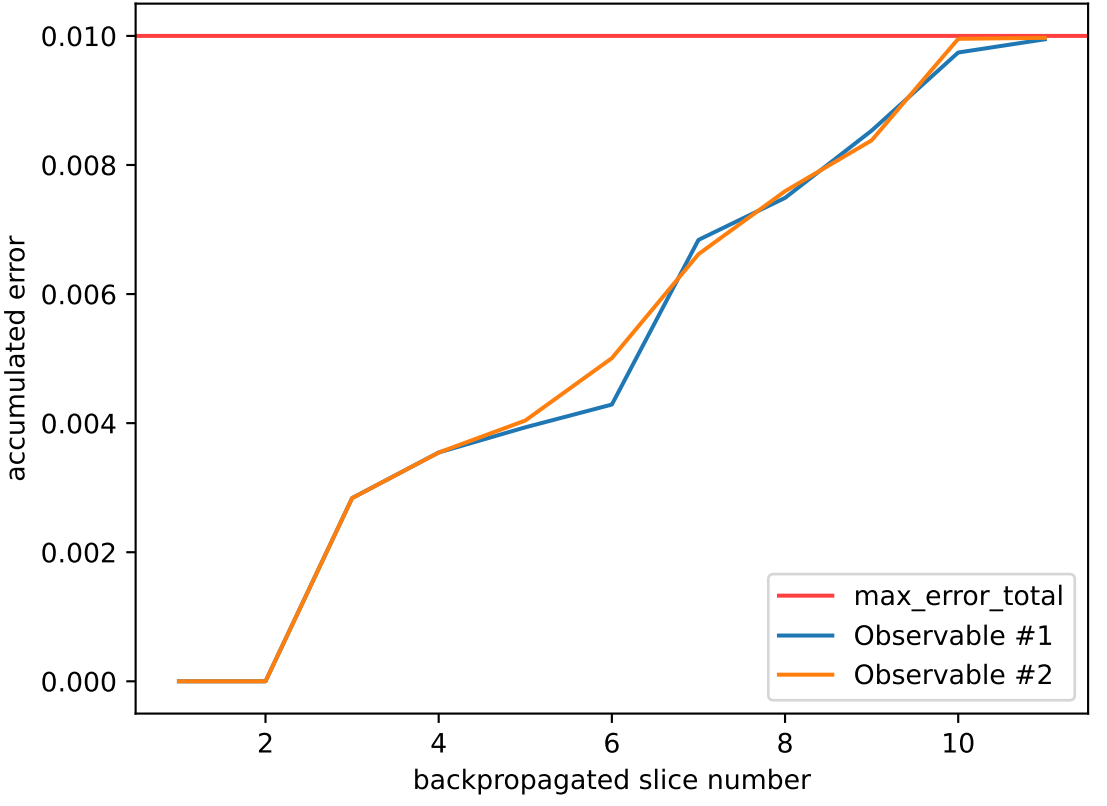
0.010
0.008
0.006
0.004
0.002
0.000
accumulated error
2
4
6
8
10
backpropagated slice number
max_error_total
Observable #1
Observable #2